

Two-dimensional simulations of strongly radiating plasmas with the RALEF-2D code

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One fluid, one temperature, two spatial dimensions (either x,y, or r,z):

$$\begin{aligned} \frac{\partial \rho}{\partial t} + \nabla \cdot \left(\rho \vec{u}\right) &= 0, \\ \frac{\partial \left(\rho \vec{u}\right)}{\partial t} + \nabla \cdot \left(\rho \vec{u} \otimes \vec{u}\right) + \nabla p &= 0, \\ \frac{\partial \left(\rho E\right)}{\partial t} + \nabla \cdot \left[\left(\rho E + p\right) \vec{u}\right] &= \nabla \cdot \left(\kappa \nabla T\right) + Q_r + Q_{dep}, \\ E &= e + \frac{u^2}{2}, \quad e = e(\rho, T) \end{aligned}$$

 $\nabla \cdot (\kappa \nabla T)$ – energy deposition by thermal conduction (local), Q_r – energy deposition by radiation (non-local), Q_{dep} – eventual external heat sources.



Transfer equation for radiation intensity I in the <u>quasi-static approximation</u>:

$$\frac{\partial I}{\partial t} + \vec{\Omega} \cdot \nabla I = k_{\nu} \left(B_{\nu} - I \right), \quad I = I \left(t, \vec{x}, \nu, \vec{\Omega} \right), \quad B_{\nu} = B_{\nu} \left(\nu, T \right)$$

<u>Quasi-static approximation</u>: radiation transports energy infinitely fast (compared to the fluid motion) \Rightarrow the energy residing in radiation field at any given time is infinitely small !

Coupling with the fluid energy equation:

$$Q_r = -\nabla \cdot \left(\int d\nu \int \vec{\Omega} I \, d\vec{\Omega} \right) = \int_{4\pi} d\vec{\Omega} \int k_v \left(I - B_v \right) \, d\nu$$

Radiation transport adds 3 extra dimensions (two angles and the photon frequency) \Rightarrow the 2D hydrodynamics becomes a 5D radiation hydrodynamics !



In many cases the term "radiation hydrodynamics" is applied to hydrodynamic equations augmented with the multi-frequency diffusion equation

$$\frac{1}{c}\frac{\partial\mathfrak{A}_{v}}{\partial t} + \nabla\cdot\left(\mathfrak{A}_{v}\frac{\vec{u}}{c}\right) + \frac{1}{3}\mathfrak{A}_{v}\nabla\cdot\left(\frac{\vec{u}}{c}\right) = \nabla\cdot\left(\frac{1}{3k_{v}}\nabla\mathfrak{A}_{v}\right) + k_{v}\left(\frac{B_{v}}{c} - \mathfrak{A}_{v}\right)$$

for the spectral radiation energy density \mathfrak{A}_{ν} ; the radiation diffusion equation is coupled to the fluid energy equation via the energy exchange term

 $Q_r = \int k_v \left(c \mathfrak{A}_v - B_v \right) dv .$

In this treatment, information about the angular dependence of the radiation field is lost (e.g. the CHIC code, P.-H. Maire, J. Breil), and the 2D hydrodynamics becomes a 3D radiation hydrodynamics.

Whereas finite-difference treatment of the <u>multi-frequency diffusion</u> is similar to that of thermal conduction, solution of the transport equation requires a completely different numerical scheme.

To solve numerically the equations of hydrodynamics in two dimensions, we employ the CAVEAT-2D (LANL, 1990) hydrodynamics package. The CAVEAT numerical

scheme has the following properties:

- it uses cell-centered principal variables on a multi-block structured quadrilateral mesh (either in the x-y or r-z geometry);
- is fully conservative and belongs to the class of secondorder Godunov schemes;
- the mesh is adapted to the hydrodynamic flow by applying the ALE (arbitrary Lagrangian-Eulerian) technique;
- the numerical method is based on a fast non-iterative Riemann solver (J.K.Dukowicz, 1985), easily applied to arbitrary equation of state.







The key ingredient to the RALEF-2D code is the **SSI (symmetric semi-implicit)** method of E.Livne & A.Glasner (1985), used to incorporate **thermal conduction** and **radiation transport** into the 2D Godunov method.

The numerical scheme for thermal conduction (M.Basko, J.Maruhn & A.Tauschwitz, J.Com.Phys., **228**, 2175, 2009) has the following features:

- it uses cell-centered temperatures from the FVD (finite volume discretization) hydrodynamics on distorted quadrilateral grids,
- is fully conservative (based on intercellular fluxes with an SSI energy correction for the next time step),
- (almost) unconditionally stable,
- **\diamond** space second-order accurate on all grids for smooth κ ,
- symmetric on a local 9-point stencil,
- computationally efficient.



Our numerical scheme for radiation transport (not published yet) has the following basic properties:

- radiation coupling to the fluid is combined with thermal conduction within the unified SSI approach;
- the angular dependence is treated by applying the classical S_n method with n(n+2) fixed photon propagation directions over the 4π solid angle;
- ✤ the scheme is **non-conservative** in the sense that energy deposition by radiation Q_r is calculated not via elementary fluxes,
- the algorithm has the important property of correct transition to the diffusion limit when mesh cells become optically thick.

Presently, we do not see any practical alternative to the SSI method to cope with numerical instabilities in cases where radiation transport has a strong dynamic impact on hydrodynamics. For each angular direction $\vec{\Omega}_L$ and frequency v, the radiation field I is found by solving the transfer equation

$$\vec{\Omega}_L \cdot \nabla I = k_\nu \left(B_\nu - I \right), \qquad I = I \left(t, \vec{x}, \nu, \vec{\Omega}_L \right),$$

with the **method of short characteristics** (A.Dedner, P.Vollmöller, JCP, **178**, 263, 2002). **Mesh nodes** are chosen as collocation points for the radiation intensity *I*.

<u>Advantages:</u>

- even on strongly distorted meshes, it is guaranteed that light rays pass through each mesh cell;
- the algorithm is generally computationally more efficient than that of long characteristics.

<u>Disadvantages:</u>

✤ a significant amount of numerical diffusion in space.

<u>Difference with R.Ramis</u>: in the MULTI-2D code I is assigned to cell edges.

Only Cartesian geometry with straight characteristics has been treated so far.





Numerical diffusion: a searchlight beam in vacuum

The method of short characteristics produces a significant amount of numerical diffusion for light beams with sharp edges.



However, for thermal radiation a certain amount of numerical diffusion may be more an advantage than a shortcoming.

Vital importance of the ALE technique

<u>The problem</u>: a thin foil is irradiated by an intense laser beam.

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<u>Problem 1:</u> A strongly radiating central Z-pinch in tungsten multi-wire arrays

Multi-wire Z-pinches (Sandia, Angara-5)

40-mm diameter array of 240, 7.5-µm-diam. wires.

Z-machine at Sandia (USA):

- 11.5 MJ stored energy
- 19 MA peak load current
- 40 TW electrical power to load
- 100-250 TW x-ray power
- 1-1.8 MJ x-ray energy

Cylindrical implosion of an initially cold tungsten plasma cloud

Initial shell parameters:

- radial thickness 2 mm;
- implosion velocity $v_0 = 400 \text{ km/s};$
- uniform temperature $T_0 = 20 \text{ eV}$;
- mass per unit length 0.286 mg/cm;
- initial kinetic energy 23 kJ/cm;
- far from the axis, mass is uniformly distributed over the radius;
- possible influence of magnetic field is neglected.

In its present formulation, the problem is <u>one-dimensional</u>.

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t = 3 ns

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Shock structure

Here we deal with a radiation-dominated shock front, which has a supercritical amplitude (see Zel'dovich and Raizer, chapter VII). The shocked material radiates away about 90% of its initial kinetic energy.

Plasma opacities

Plasma opacities for the above simulation have been provided by the group of V.G.Novikov from the Keldysh institute (KIAM) with the THERMOS code.

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Total X-ray emission power

The imploding tungsten plasma radiates away about 90% of its initial kinetic energy.

The nominal power of implosion is

$$W_{nom} = \frac{1}{2} M U_{im}^2 / t_{pulse} =$$

= 23 kJ cm⁻¹/5 ns = 4.6 TW cm⁻¹

Spatially integrated emission spectra

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High-resolution emission spectra can be obtained in the post-processor regime even when hydrodynamics is simulated with a relatively small number (~10) of spectral groups.

Optical thickness of the imploding plasma

Calculated X-ray images of the central pinch

Spectral X-ray images provide information on the internal structure of the imploding pinch.

<u>Problem 2:</u> Hole boring in a copper foil by an intense nanosecond laser pulse

Copper foil under PHELIX (GSI) irradiation

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Simulation setup

hv (keV)

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Time dependence of mass column density $\int \rho dx$ along the central axis at y = 0.

The effect of hole boring:

the evacuated mass exceeds the depth of the critical surface by as large a factor as 20–30.

The status of the RALEF-2D code:

- the first results are encouraging,
- the work on further development continues.